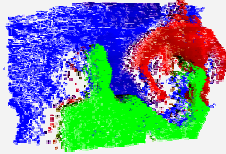


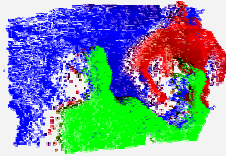
Kurzprofil Prof. Dr.-Ing. Hubert Roth

| | |
|---------------------------------------|--|
| Geburtsdatum | 21.03.1954 |
| Studium, 1974-1979 | Elektrotechnik an der Universität Karlsruhe mit Schwerpunkt in Regelungstechnik und Informatik |
| 1979-1983 | Wissenschaftlicher Mitarbeiter am Institut für Regelungs- und Steuerungssysteme (Prof. Dr. Dr. Föllinger) der Universität Karlsruhe |
| Promotion, 1983 | Ein neues Verfahren zur Ordnungsreduktion und Reglerentwurf auf der Basis reduzierter Modelle |
| 1983-1988 | Systemingenieur bei der Fa. Dornier System, Bereich Raumfahrt, Abteilung Regelungstechnik |
| 1988-2000 | Professor für Regelungs- und Sensortechnik an der Fachhochschule Ravensburg-Weingarten |
| 2000-2001 | Lehrstuhlvertretung in der Fachgruppe für Regelungs- und Steuerungstechnik an der Universität Siegen |
| Seit 2001 | Leiter der Fachgruppe für Regelungs- und Steuerungstechnik im Fachbereich Elektrotechnik und Informatik der Universität Siegen |
| 2000 | Übernahme der Leitung des Projektbereichs 4, "Automation, Mechatronik und Medizintechnik" im Zentrum für Sensorsysteme (ZESS) |
| Forschungspreise 2001 | <ul style="list-style-type: none">• Verleihung des Schweizer Innovationspreises, St. Gallen, Schweiz• Verleihung des Kulturpreises der Städte Ravensburg und Weingarten, Weingarten |
| Lehrgebiete: | <ul style="list-style-type: none">• Regelungstechnik,• Robotik• Mechatronische Systeme (in Englisch)• Advanced Control (in Englisch)• Intelligent Control (in Englisch)• Attitude Control for Space Applications (in Englisch) |
| Forschungs- u. Arbeitsgebiete: | <ul style="list-style-type: none">• Navigation und Lokalisation bei kooperierenden mobilen Robotern• Regelung in der Luft- und Raumfahrt• Bahnplanung und Hindernisvermeidung bei Manipulatoren• Tele-Control, Tele-Manipulation, Tele-Präsenz• E-learning |
| Aktuelle Vorhaben | <ul style="list-style-type: none">• Navigation mobiler Roboter mit Hilfe der PMD-Kamera• Search and Rescue Robotics• Outdoor Robotics• Environmental Exploration (E²N) |
| Aktuell: | <ul style="list-style-type: none">• Seit 1992 Leiter des Steinbeis-Transferzentrums „Angewandte Rechner- und Software-Technologien“• Seit 1994 Mitglied im "Technical Committee on Components and Instruments" der "International Federation of Automatic Control"• Seit 2002 Leiter des "Technical Committee on Computers and Telematics" der "International Federation of Automatic Control" |
| Weitere Informationen | http://www.uni-siegen.de/rst |

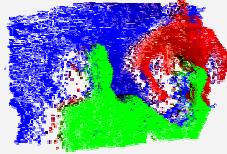


Schriftenverzeichnis Prof. Dr.-Ing. Hubert Roth

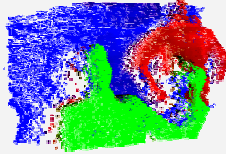
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